YASKAWA

Segment: Automobile Industry Application: Case Study of Machine Tending Organization: Yaskawa India Pvt.Ltd.

Description:

Yaskawa is supplying robotic Handling system for Automobile Industries. In this system Gear will Pick from Double decker conveyor & place it on Hobbing and chamfering machines.

Objective: Automated solution for placing Gears on two machine's and final component placed on same conveyor.

System Overview:

Operator placed 114 component's on double decker slide conveyor which travels on THK rails with the help of Pneumatic cylinders. When cycle start given, at a time one slide go ahead towards robot at fix position & robot pick component from there. That component placed on Hobbing m/c & output of Hobbing m/c placed on teeth confirmation SPM where teeth position confirmed, and that part placed on clipping machine. Output of clipping machine placed on slide conveyor.

Scope of supply:

- Robot : MH24
- Controller : DX200
- Communication Protocol : Hardwiring
- PLC: Allen Bradley
- HMI Proface
- Dual Gripper (Pneumatic Schunk gripper)
- Safety Fence & Safety Door
- Poka Yoke Station for gear teeth matching.
- PLC panel & Operational Panel
- Variants Proved: 12

Application Layout:



Actual Site Images:





System Engineering

EMPTY POSITION



INPUT & OUTPUT STATION

- > NUMBER OF GEARS PER PALLET- 57 NOS
- TOTAL NUMBER OF GEARS PER LOADING 114 NOS
- OPERATOR LOADS 114 COMPONENTS AT A TIME
- > BOTH PLATES MOVE THRU PNEUMATIC CYLINDERS SEPERATELY
- ➢ COMPONENT CYCLE TIME- 125 SEC
- LOAD / UNLOAD FREQUENCY FOR 114 PARTS -4 HOURS
- > ONE EMPTY FIXTURE FOR OUTPUT PURPOSE
- NEW COMPONENT SETUP CHANGE OVER 15 MINS



COMPONENT LOCATION



FIXTURE FOR COMPONENT LOCATION WRT INNER DIAMETER FOR 5 DIFFERENT VARIANTS



GAUGE PLATE FOR ALL FIXTURE TO SET THE PINS ACCORDING TO 5 DIFFERENT COMPONENT VARIANT ID.



QUICK ADJUSTMENT ARRANGEMENT FOR COMPONNT VARIANTS (REDUCE CHANGING TIME)

DUAL GRIPPERS



GEAR TEETH MATCHING STATION





